



No.	Name	Description	Default
	selection		
P28.02	Master/slave control mode	Ones place: Master/slave running mode selection 6: Master/slave mode 6 Used for master/slave height transfer, in which the master sends the measured height to the slave. (You can check P94.05 to obtain the height sent from the master and P94.32 to obtain the height sent to the slave.) Tens place: Slave start command source 0: Master 1: Determined by P00.01 Hundreds place: Whether to enable master/slave to send/receive data 0: Enable 1: Disable	0x116
Height measuring			
P93.08	Enabling height measuring	0–1 0: Disable 1: Enable internal measuring (motor encoder) (In closed-loop mode, the encoder measures the speed and height.) 2: Enable external measuring (HDI) (In open- and closed-loop modes, the pulley encoder measures the height.)  	1
P93.09	Mechanical transmission ratio	0.01–300.00	10.00
P93.10	Suspension ratio	1–4	1
P93.11	Rope length compensation	0.00–50.00m	0.00
P93.12	Cable diameter	0.1–100.0m	10.0mm
P93.13	Per-layer turns of drum winding	1–200	30
P93.14	Initial turns of drum winding	0–P93.11 (Per-layer turns of drum winding)	0

